Nr.74 - 1987

The description of an $\ensuremath{\mathbb{R}^n}\xspace$ -valued one form relative to an embedding

E.Binz

(Universität Mannheim)

The description of an \mathbb{R}^n -valued one form relative to an embedding

E.Binz

1) Introduction

Let M be a compact, smooth and oriented manifold. The collection of all smooth embeddings of M into \mathbb{R}^n equipped with the C[∞]-topology is a Fréchet manifold and is denoted by $\mathbb{E}(M,\mathbb{R}^n)$. The collection $A^1(M,\mathbb{R}^n)$ consisting of all smooth \mathbb{R}^n -valued one forms of M, also endowed with the C[∞] topology, is a Fréchet space. \mathbb{R}^n is assumed to be oriented and is equipped with a fixed scalar product <,> .

These notes describe relations between a given $\alpha \in A^1(M,\mathbb{R}^n)$ and a given $i \in E(M,\mathbb{R}^n)$. Two sorts of decomposition of α relative to i are discussed and related. First we show that α splits into

 $\alpha = dh + \beta \quad h \in C^{\infty}(M, \mathbb{R}^{n})$,

where β has only the zero as integrated parts. The other decomposition is $\alpha = c_{\alpha}(i) \cdot di + di \cdot C_{\alpha}(i) + di \cdot B_{\alpha}(i)$

with $c_{\alpha} \in C^{\infty}(M, so(n))$ and $C_{\alpha}(i)$ as well as $B_{\alpha}(i)$ are smooth, strong bundle maps of TM skew-, respectively selfadjoint with respect to the Riemannian metric m(i), the pullback of < > by i.

The relation among these two splittings as well as the techniques presented play a crucial role in elasticity theory.

Smoothness is always meant in the sense of [Gu].

2) Relations between α and i

Throughout these notes $i \in E(M,\mathbb{R}^n)$ is a fixed (smooth) embedding and $\alpha \in A^1(M,\mathbb{R}^n)$ a fixed (smooth) \mathbb{R}^n -valued one form di $\in A^1(M,\mathbb{R}^n)$ is locally given by the Fréchet derivative of i. Clearly m(i)(X,Y)=<di X,di Y> for all X,Y $\in \Gamma$ TM.

Our first observation is as follows:

<u>Proposition 1</u> Given $\alpha \in A^1(M,\mathbb{R}^n)$ and $i \in E(M,\mathbb{R}^n)$ then there is a map $h(i) \in C^{\infty}(M,\mathbb{R}^n)$, determined up to a constant such that

(1)
$$\alpha = dh(i) + \beta(i)$$

h(i) is called the integrable part of α . The decomposition (1) of α is maximal in the sense that the integrable part of $\beta(i)$ is zero

<u>Proof</u>: Let e_1, \ldots, e_n be an orthonormal basis of \mathbb{R}^n . Then

$$\alpha(X) = \sum_{s=1}^{n} \alpha^{s}(X)e_{s} \quad \forall X \in \Gamma TM$$

for a uniquely determined family $\alpha^1, \ldots, \alpha^n \in A^1(M,\mathbb{R})$ of smooth \mathbb{R} -valued one forms of M. Clearly

$$a^{S}(X) = \langle a(X), e_{S} \rangle$$

For each s = 1,...,n the one form α^{S} can be represented as $\alpha^{S}(X) = m(i)(Y_{S},X)$ for all $X \in \Gamma TM$

for a well defined $Y_s \in \Gamma TM$. This vector field splits according to Hodge's decomposition uniquely into

$$Y_s = \text{grad}_i \tau_s + Y_s^0$$

where $\text{grad}_i \tau_s$ means the gradient of $\tau_s \in C^{\infty}(M,\mathbb{R})$ with respect to the metric m(i) and $\text{div}_i Y^0 = 0$. By div_i we denote the divergence operator associated with m(i). Thus

$$\alpha^{s}(X) = d\tau_{s}(X) + m(i)(Y_{s}^{0},X)$$

Now we define

h(i): = $\sum_{s=1}^{n} \tau_s \cdot e_s$

and

$$\beta(i)(X) := \sum_{s=1}^{n} m(i)(Y_{s}^{o}, X) \cdot e_{s} \quad \forall X \in \Gamma TM .$$

Then

$$\alpha = dh(i) + \beta(i)$$

Let us verify that this decomposition does not depend on the basis chosen. To this end let $\bar{e}_1, \ldots, \bar{e}_n \in \mathbb{R}^n$ be any other orthonormal basis of \mathbb{R}^n and define $\bar{\alpha}^{S}, \bar{\tau}_{S}, \bar{Y}_{S}^{O}, \bar{h}$ and $\bar{\beta}$ analoguously as above. Omiting the variable i then for any $\bar{s} = 1, ..., n$

$$\begin{split} \bar{\alpha}^{S}(X) &= < \alpha(X), \ \bar{e}_{\bar{s}} > = < dh(X), \ \bar{e}_{\bar{s}} > + < \beta(X), \ \bar{e}_{\bar{s}} > = \\ &= < \sum_{1}^{n} d\tau_{\bar{s}}(X) \cdot e_{\bar{s}}, \\ \bar{e}_{\bar{s}} > + < \sum_{1}^{n} m(i)(Y_{\bar{s}}^{0}, X) \cdot e_{\bar{s}}, \\ \bar{e}_{\bar{s}} > \\ &= m(i)(grad_{\bar{i}} \sum_{1}^{\Sigma})(\tau_{\bar{s}} \cdot e_{\bar{s}} \\ \bar{e}_{\bar{s}} >), \\ X) + m(i)(\sum_{1}^{n} Y_{\bar{s}}^{0} \cdot e_{\bar{s}}, \\ \bar{e}_{\bar{s}} > + \\ &= m(i)(grad_{\bar{i}} \ \bar{\tau}_{\bar{s}}, \\ X) + m(i)(Y_{\bar{s}}^{0}, \\ X) \end{split}$$

Since $\operatorname{grad}_{i} \xrightarrow{\Sigma}_{s} (\tau_{s} < e_{s}, e_{\overline{s}})$ is a gradient with respect to m(i) and since $\operatorname{div}_{i}(\Sigma Y_{S}^{0} < e_{S}, \overline{e}_{\overline{S}}) = 0$

we conclude due to the uniqueness of Hodge's decomposition

$$grad_{i} \sum_{s=1}^{n} (\tau_{s} \cdot \langle e_{s}, e_{\bar{s}} \rangle) = grad_{i} \overline{\tau}_{s}$$

$$n_{\Sigma} Y_{s}^{0} \langle e_{s}, \overline{e}_{\bar{s}} \rangle = Y_{\bar{s}}^{0} .$$

and

Thus for any
$$X \in \Gamma TM$$
 we have
 $dh(X) = \sum_{\bar{S}=1}^{n} \langle dh(X), \bar{e}_{\bar{S}} \rangle \bar{e}_{\bar{S}} = \sum_{\bar{S}=1}^{n} \langle d\bar{h}(X), \bar{e}_{\bar{S}} \rangle \bar{e}_{\bar{S}} = d\bar{h}(X)$
and
 $\beta(X) = \sum_{\bar{S}=1}^{n} \langle \beta X \rangle, \bar{e}_{\bar{S}} \rangle \bar{e}_{\bar{S}} = \Sigma \langle \bar{\beta}(X), \bar{e}_{\bar{S}} \rangle \bar{e}_{\bar{S}} = \bar{\beta}(X)$

and

Let us investigate the decomposition (1) in proposition 1 somewhat closer. We have

$$\alpha = dh(i) + \beta(i)$$

for some $h \in C^{\infty}(M,\mathbb{R}^n)$. Obviously

$$h(i) = di X_n + h^{\perp}(i)$$

for some well-defined $X_h \in \Gamma TM$. By $h^{\perp}(i)$ we denote the pointwise formed component of h normal to i(M). The vector field X_h again decomposes according to Hodge's decomposition into

 $X_h = X_h^0 + \operatorname{grad}_i \psi_h$ with div $X_h^0 = o$ and $\psi_h \in C^{\infty}(M,\mathbb{R})$.

3

Hence

dh(i)X = di ⊽(i)_X X⁰_h + di(⊽(i)_X grad_i
$$\Psi_h$$
 + W(i)_h X)
+ S(i)(X_h,X) .

Here diW(i)_h X = dh[⊥](i)(X)^T, where the upper indices T and ⊥ denote the pointwise formed component tangential respectively normal to i(M). We remind the reader that $W_h(i)$ is a smooth strong bundle endomorphism of TM 'selfadjoint with respect to m(i). Let now h¹ = h + z for some $z \in \mathbb{R}^n$. Then if we regard z as a constant map in C[∞](M,R) we again have $z = \operatorname{di} X_z + z^{\perp}$.

However the vector field on \mathbb{R}^n assigning to any $z' \in \mathbb{R}^n$ the vector $z \in \mathbb{R}^n$ is a gradient of some map $\varphi \in C^{\infty}(\mathbb{R},\mathbb{R})$ say. Hence if we form $\varphi \circ i$ then

$$X_7 = \text{grad}_i(\phi \circ i)$$
 .

Therefore

$$h^{1}(i)^{T} = di X_{h}^{0} + grad_{i}(\Psi_{h} + \varphi \circ i)$$

= di $X_{h1}^{0} + grad_{i} \Psi_{h1}$.

Again due to the uniqueness of Hodge's decomposition of X_{h1} we conclude:

<u>Proposition 2</u> Given $\alpha \in A^1(M,\mathbb{R}^n)$ and $i \in E(M,\mathbb{R}^n)$, then if the splitting $\alpha = dh(i) + \beta(i)$ is maximal for some $h(i) \in C^{\infty}(M,\mathbb{R}^n)$ determined up to a constant and if for some $h^1(i) \in C^{\infty}(M,\mathbb{R}^n)$ with $h^1(i) = h(i)+z$ and $z \in \mathbb{R}^n$ $\alpha = dh^1(i) + \beta(i)$

then

$$X_h^o = X_{h1}^o$$
.

Here X_h^0 and $X_h^0 1$ denotes the divergence free part of X_h and $X_h 1$ respectively.

Next we will study $\alpha \in A^1(M,\mathbb{R}^n)$ in relation to a fixed $i \in E(M,\mathbb{R}^n)$ from a quite different point of view.

For any pair X,Y we set

 $T(\alpha,i)(X,Y) : = < \alpha(X), di Y >$

Hence $T(\alpha,i)$ is a smooth two tensor on M, splitting uniquely into a symmetric and an antisymmetric part $T(\alpha,i)^s$ and $T(\alpha,i)^a$ respectively. If P : TM \longrightarrow TM denotes the unique smooth strong bundle endomorphism for which

$$T(\alpha,i)(X,Y) = m(i)(PX,Y)$$

then

$$T(\alpha,i)^{S}(X,Y) = m(i)(\frac{1}{2}(P + \tilde{P})X,Y)$$

and

$$T(\alpha,i)^{a}(X,Y) = m(i)(\frac{1}{2}(P - \tilde{P})X,Y)$$
.

Here \tilde{P} denotes the fibrewise formed adjoint of P with respect to m(i). Let us set $B_{\alpha}(i) = \frac{1}{2}(P + \tilde{P})$ and $C_{\alpha}(i) = \frac{1}{2}(P - \tilde{P})$.

Therefore

 $\alpha(X) = \alpha^{1}(X) + di C_{\alpha}X + di B_{\alpha}X$

holds for any $X \in \Gamma TM$. Clearly $\alpha^1(X)(p)$ is a vector in the normal space of Ti T_pM for each $p \in M$. Hence there is a unique smooth

5

$$c_{\alpha} \in C^{\infty}(M, so(n))$$

where so(n) denotes the Lie algebra of SO(n) such that

$$x^{\perp}(X) = c_{\alpha} \cdot di X \quad \forall X \in \Gamma TM.$$

Thus we may state that a second decomposition of α relative to i :

Proposition 3 Given $\alpha \in A^1(M,\mathbb{R}^n)$ and $i \in E(M,\mathbb{R}^n)$ there are uniquely determined smooth, strong bundle endomorphisms

$$C_{\alpha}(i) : TM \longrightarrow TM$$

 $B_{\alpha}(i) : TM \longrightarrow TM$

and

which are with respect to m(i) skew-respectively selfadjoint and there is a uniquely determined $c_{\alpha}(i) \in C^{\infty}(M, so(n))$ such that the following relation holds for all $X \in \Gamma TM$:

(2)
$$\alpha(X) = c_{\alpha}(i) \cdot di X + di \cdot C_{\alpha}(i)X + di \cdot B_{\alpha}(i)X .$$

<u>Remark:</u> Given $\alpha \in A^1(M, \mathbb{R}^n)$ and $i \in E(M, \mathbb{R}^n)$ then the exterior differential $\Im^T(\alpha, i)^a$ of $T(\alpha, i)^a$ satisfies

(3)
$$\partial T^{a}(\alpha,i) = 0$$
 iff $\partial \alpha = 0$.

The reason is that the one-form $< i, \alpha > \in A^1(M,\mathbb{R})$ assigning to any $X \in \Gamma TM$ the function $< i, \alpha(X) >$ satisfies

$$\partial < i, \alpha > = T(i, \alpha)^{a}$$
 iff $\partial \alpha = 0$

Now we will link the two descriptions of α relative to i as expressed by the two propositions (1) and (2). To this end let $\alpha \in A^1(M,\mathbb{R}^n)$ and $i \in E(M, \mathbb{R}^n)$ be given. Let

 $\alpha = dh(i) + \beta(i)$

be the decomposition described in proposition (1). We split h(i) into

6

 $h(i) = di X_h + h^{\perp}(i)$.

Hence for any $Y \in \Gamma TM$

(4)
$$dh(i)Y = di \nabla(i)_{Y} X_{h} + W_{h}(i)Y +$$

+ $S(i)(Y,X_{n}) + (d(h^{\perp})(Y))^{\perp} + \beta(Y)$

Forming T(dh,i), decomposing it into $T(dh,i)^S$ and $T(dh,i)^a$ and using (4) yields immediately

$$T(dh,i)^{s}(X,Y) = m(i)(X,\nabla(i)_{Y}X_{h}) + m(i)(X,W_{h}(i)Y)$$

Therefore

and

$$T(dh,i)^{a}(X,Y) = \frac{1}{2}(m(i)(X,\nabla(i)_{Y}X_{h}) - m(i)(Y,\nabla(i)_{X}X_{h}))$$

$$T(dh,i)^{s}(X,Y) = \frac{1}{2}(m(i)(X,\nabla(i)_{Y}X_{h}) + m(i)(Y,\nabla(i)_{Y}X_{h}))$$

$$+ m(i)(X,W_{h}(i)Y) = \frac{1}{2}L_{X_{h}}(m(i))(X,Y) + m(i)(X,W_{h}(i)Y)$$

Here $L_{X_h}(m(i))$ is the Lie derivative of m(i). Writing for any $Z \in \Gamma TM$

$$L_{\mathbb{Z}'_{h}}(\mathfrak{m}(\mathfrak{i}))(X,Y) = \mathfrak{m}(\mathfrak{i})(\mathbb{L}_{\mathbb{Z}'_{h}} X,Y)$$

where

$$L_{\mathbb{Z}}$$
 : TM \longrightarrow TM

is a strong smooth bundle endomorphism given by the theorem of Fischer-Riesz, then $c_{\alpha}(i)$, $C_{\alpha}(i)$ and $B_{\alpha}(i)$ relate to h as follows

(5)
$$c_{\alpha}(i)di Y = (d(dh^{\perp}(i))Y)^{\perp} + S(i)(Y,X_{h}) + C_{\alpha}(i) \cdot di Y$$

(6)
$$C_{\alpha}(i)Y = \frac{1}{2} (\nabla(i)X_{h} - \widetilde{\nabla}(i)X_{h})Y + C_{\beta}(i)Y$$

and

$$B_{\alpha}(i)Y = \frac{1}{2} (\nabla(i)X_{h} + \widetilde{\nabla}(i)X_{h})Y + W(i)_{h}Y + B_{\beta}(i)Y =$$

= $(\frac{1}{2} L_{X_{h}}(i) + W(i)_{h} + B_{\beta}(i))Y$.

Here $\widetilde{\nabla}(i) X_h$ means the fibrewise formed adjoint with respect to m(i), which applied to $v_p \in T_p M$ is written as $\widetilde{\nabla}(i) X_h(v_p)$ for any $p \in M$. If we split furthermore X_h into

7

$$X_h = X_h^0 + \text{grad}_i \psi$$
 with $\text{div}_i X_h^0 = 0$

(according to Hodge's decomposition) and taking

$$0 = m(i)((\nabla(i)\text{grad}_{i}\Psi - \tilde{\nabla}(i) \text{ grad}_{i}\Psi) X, Y) = 0$$

into account yields finally the desired relations

Proposition 4 Let $\alpha \in A^1(M, \mathbb{R}^n)$ and $i \in E(M, \mathbb{R}^n)$. Given any $h(i) \in (M, \mathbb{R}^n)$ with

$$h(i) = di X_{h}(i) + h^{\perp} = X_{h}(i)^{\circ} + grad_{i}\psi(i) + h^{\perp}$$

as split according to the Hodge decomposition of X_h and $\alpha = dh(i) + \beta(i)$

then the coefficients in

$$\alpha = c_{\alpha}(i) \cdot di + di C_{\alpha}(i) + di B_{\alpha}(i)$$

are determined by

(8)
$$c_{\alpha}(i) \cdot di = d(dh^{\perp}(i))^{\perp} + S(i)(X_{h}(i), ...) + c_{\beta} \cdot di$$

(9)
$$C_{\alpha}(i) = \frac{1}{2}(\nabla(i)X_{h}(i) - \widetilde{\nabla}(i)X_{h}(i)) + C_{\beta}(i)$$

$$= \frac{1}{2}(\nabla(i)X_{h}(i)^{\circ} - \widetilde{\nabla}(i)X_{h}(i)^{\circ}) + C_{\beta}(i)$$

and

(10)
$$B_{\alpha}(i) = \frac{1}{2} L_{X_{h}}(i)^{\circ} + \operatorname{grad}_{i} \psi(i)^{+} W_{h}(i) + B_{\beta}$$

Hence

(11)
$$\operatorname{tr} B_{\alpha}(i) = \operatorname{div} X_{h}(i) + \operatorname{tr} W_{h}(i) + \operatorname{tr} B_{\beta} = - \nabla(i) \Psi(i) + \operatorname{tr} W_{h}(i) + \operatorname{tr} B_{\beta}$$

with $\nabla(i)$ is the Laplace Beltrami operator of m(i) .

The rest of this section is devoted to the covariant divergence of $B_{h}(i)$ and $C_{h}(i)$. The covariant divergence div_iA of any smooth strong bundle endomorphism

$$A : TM \longrightarrow TM$$

is defined as follows: Let e_1, \ldots, e_m be any moving orthonormal frame of TM . Then r=m

(12)
$$\operatorname{div}_{i} A = \sum_{r=1}^{r} \nabla(i)_{e_{r}}(A) e_{r}$$

First we compute $div_i \nabla(i)X_h$. For any $Y \in \Gamma TM$ the equation

$$m(i)(\nabla(i)_{e_{r}}(\nabla(i)X_{h})e_{r},Y) = m(i)(\nabla(i)_{e_{r}}(\nabla(i)_{e_{r}}X_{h})-\nabla(i)_{\nabla(i)_{e_{r}}}e_{r}^{X_{h},Y)}$$

implies

(13)
$$\operatorname{div}_{i} \nabla(i) X_{h} = -\Delta(i) X_{h}$$

 $\Delta(i)$ being the Laplace Beltrami operator of m(i). To find div_i $\tilde{\forall}(i)X_h$ consider for any Y $\in \Gamma TM$ the equations

$$\begin{split} \mathfrak{m}(i)(\nabla(i)_{e_{r}}(\widetilde{\nabla}(i)X_{h})e_{r},Y) &= e_{r}(\mathfrak{m}(i)(\widetilde{\nabla}(i)X_{h}(e_{r}),Y)) - \mathfrak{m}(i)(\widetilde{\nabla}(i)X_{h}(\nabla(i)e_{r}e_{r}),Y) \\ &- \mathfrak{m}(i)(\widetilde{\nabla}(i)X_{h}(e_{r}), \nabla(i)e_{r}Y) \\ &= \mathfrak{m}(i)(e_{r},\nabla(i)e_{r}\nabla(i)Y_{h}) - \mathfrak{m}(i)(e_{r},\nabla(i)\nabla(i)e_{r}Y_{h}) \\ &= \mathfrak{m}(i)(e_{r},\nabla(i)e_{r}(\nabla(i)X_{h})Y) \end{split}$$

and

$$\begin{split} \mathfrak{m}(i)(\nabla(i)_{\gamma}(\widetilde{\nabla}(i)X_{h})e_{r},e_{r}) &= \mathfrak{m}(i)(e_{r},\nabla(i)_{\gamma}\nabla(i)e_{r}X_{h}) - \mathfrak{m}(i)(e_{r},\nabla(i)_{\nabla}(i)_{\gamma}e_{r}X_{h}) \\ &= \mathfrak{m}(i)(e_{r},\nabla(i)_{\gamma}(\nabla(i)X_{h})e_{r}) \ . \end{split}$$

Thus we find

$$\begin{array}{c} m \\ \Sigma \\ r=1 \end{array} (m(i)(\nabla(i)_{e_{r}} (\widetilde{\nabla}(i)X_{h})e_{r},Y) - m(i)(\nabla(i)_{\gamma} (\widetilde{\nabla}(i)X_{h})e_{r},e_{r})) \\ = \operatorname{Ric}(m(i))(Y,X_{h}) \end{array}$$

and consequently

 $m(i)(div_i \widetilde{\nabla}(i)X_h, Y) = tr \nabla(i)_Y(\nabla(i)X_h) + Ric(m(i))(Y, X_h)$.

9

Here Ric(m(i)) denotes the Ricci tensor of m(i). The last equation yields

(14)
$$\operatorname{div}_{i} \widetilde{\nabla}(i) X_{h} = \operatorname{grad}_{i} \operatorname{div}_{i} X_{h} + R(i) X_{h}$$

Here Ric(i)X_h is defined via

Now we immediately conclude

(15) div
$$\not = \Delta(i)X_h + R(i)X_h + grad div X_h$$

(16) 2 div
$$C_h(i) = -\Delta(i)X_h - R(i)X_h$$
 - grad div X_h

showing

(17)
$$\operatorname{div}_{i}(\frac{1}{2} \operatorname{L}_{X_{h}}(i) + C_{h}(i)) = -\Delta(i) X_{h}$$

and

(18)
$$\operatorname{div}(\frac{1}{2} \mathbb{L}_{\chi_{h}}(i) - C_{h}(i) = \operatorname{Ric}(i) X_{h} + \operatorname{grad}_{i} \operatorname{div}_{i} X_{h}$$
.

These equations will be of interest later.

Let us restrict our attention to the case of

 $1 + \dim M = n$.

Then since M is oriented we have the oriented unite normal vector field N(i) along i. Hence $h \in C^{\infty}(M, \mathbb{R}^{n})$ splits into

 $h(i) = di X_h + \tau(i) \cdot N(i)$

for some $\tau(i)\in C^\infty(M,\!\!\!\!R)$. Thus $W_h(i)=W(i)$ if $\tau=1$. Denoting tr W(i) by H(i) we immediately find

$$m(i)(div_{i}(\tau(i) \cdot W(i)), Y) = \sum_{r=1}^{m} m(i)(\nabla(i)e_{r}(\tau(i)W(i))e_{r}, Y) = \sum_{r=1}^{m} m(i)(grad_{i}\tau(i), W(i)Y) + m(i)(\tau(i)div_{i}W(i), Y)$$

$$r=1$$

and hence

(19)
$$\operatorname{div}_{i}(\tau(i)W(i)) = W(i)\operatorname{grad}_{i}\tau(i) + \tau(i)\operatorname{div}_{i}W(i) .$$

Now by Codazzi's equation (cf.[K1]) yields

(20)
$$\sum_{r=1}^{m} m(i)(\nabla(i)_{e_r}(W(i))e_r,Y) = \sum_{r=1}^{m} m(i)(\nabla(i)_{\gamma}(W(i))e_r,e_r) =$$
$$= m(i)(\text{grad } H(i),Y) .$$

We therefore have

(21)
$$\operatorname{div}_{i}\tau(i)W(i) = W(i)\operatorname{grad}_{i}\tau(i) + \tau(i)\operatorname{grad}_{i}H(i) .$$

In turn equations (19),(20),(9),(10),(15),(16),(17) and (18) yield

(22)
$$\operatorname{div}_{i}(B_{h}(i) + C_{h}(i)) = -\Delta(i)X_{h} + W(i)\operatorname{grad}_{i}\tau(i)+\tau(i)\operatorname{grad}_{i}H(i)$$
and

(23)
$$\operatorname{div}(B_{h}(i) - C_{h}(i)) = R(i) X_{h} + \operatorname{grad}_{i} \operatorname{div}_{i} X_{h} + W(i)\operatorname{grad}_{i} \tau(i) + \tau(i)\operatorname{grad}_{i} H(i) .$$

We close this section by showing the following result:

Lemma 5 Let $\alpha \in A^1(M,\mathbb{R}^n)$ and $i \in E(M,\mathbb{R}^n)$. If α has no integrable part then $\alpha = \beta$ and hence

(24)
$$\operatorname{div}_{i}(C_{\beta}(i) + B_{\beta}(i)) = 0$$

<u>Proof:</u> We have for any $X \in rTM$ $\alpha(X) = \beta(X) = \sum_{\substack{x = 1 \\ s=1}}^{m} m(i)(Y_s^0, X)\bar{e}_s$

and any orthonormal frame $\bar{e}_1, \ldots, \bar{e}_n$ in \mathbb{R}^n .

Hence

$$< \alpha(X), di Y > = m(i)((C_{\beta}(i) + B_{\beta}(i))X, Y) = \sum_{s=1}^{m} m(i)(Y_{s}^{o}, X) < \overline{e}_{s}, di Y > S = 1$$

Thus if e_1, \ldots, e_m is a moving orthonormal frame in TM , then $m(i)(div_i(C_{\beta}(i)+B_{\beta}(i)), Y) = \sum_{r=1}^{\infty} \sum_{s=1}^{\infty} m(i)(\nabla(i)e_r Y_s^{o}, e_r) < \bar{e}_s, di Y > e_r < \bar{e}_s$

Interchanging the summation yields (24).

Therefore we have due to (24) and (22)

<u>Corollary 6</u> Let $\alpha \in A^1(M_{J}R^n)$ and $i \in E(M_{J}R^n)$ and let $\alpha = dh+\beta$ as in (1). If $h(i) = di X_1 + \tau \cdot N(i)$ then

$$div_{i}(B_{\alpha}(i) + C_{\alpha}(i)) = div(B_{h}(i) + C_{h}(i)) =$$

= - $\Delta(i)X_{h}$ + W(i)grad_i $\tau + \tau \cdot grad_{i}H(i)$.

References:

[Gu]

Gutknecht J.

"Die C_{Γ}^{∞} -Struktur auf der Diffeomorphismengruppe einer kompakten Mannigfaltigkeit". Diss.ETH 5879, Zürich 1977.

[K1]

Klingenberg W.

"Riemannian Geometry", de Gruyter Series in Mathematics (1982), Walter de Gruyter, Berlin, New York.